

# Solutions to Holdener Review packet.

#1 a)  $f_x(S) < f_y(Q) < 0 < f_x(P) < f_y(R)$

b)  $f_{xx}(P) > 0$  because the slice of  $z = f(x, y)$  parallel to the  $x$ -axis at  $P$  is concave up.

#2. 
$$f_x(x, y) = \frac{\sqrt{x^2 + y^2} \cdot 2y^2 - 2xy^2 \cdot \frac{1}{2} \cdot \frac{1}{\sqrt{x^2 + y^2}}}{x^2 + y^2} (2x)$$

#3.  $f(x, y) = x^3 + 6xy - 2y^2 + 1$ ,  $f_{\vec{u}}(1, 1) = ?$

$$\nabla f(x, y) = \langle 3x^2 + 6y, 6x - 4y \rangle$$

$$\nabla f(1, 1) = \langle 9, 2 \rangle \quad \hat{u} = \left\langle \frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}} \right\rangle$$

$$f_{\vec{u}}(1, 1) = \langle 9, 2 \rangle \cdot \left\langle \frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}} \right\rangle = \frac{18}{\sqrt{5}} + \frac{2}{\sqrt{5}} = \frac{20}{\sqrt{5}} = \boxed{4\sqrt{5}}$$

#4. To say  $f_{\vec{u}} = \nabla f$  is complete nonsense because  $f_{\vec{u}}$  is a number (the slope of  $z = f(x, y)$  at  $P$  in the direction of  $\vec{u}$ ) while  $\nabla f$  is a vector (the direction of greatest initial increase of  $f$  at  $P$ ). Bubba should have stated that  $f_{\vec{u}} = \|\nabla f\|$ . (Indeed, in the situation given,  $\vec{u}$  is perpendicular to the contour at  $P$ .)

#5. The differential  $df$  is defined by  $df = f_x dx + f_y dy$ .  $df$  estimates  $\Delta f = f(x+dx, y+dy) - f(x, y)$  for small  $dx$  &  $dy$ .

#6. Informally, we say that  $f$  is differentiable at a point  $(a, b)$  if  $f$  is locally planar at  $(a, b)$ . Formally,  $f$  is differentiable if

$$\lim_{\substack{h \rightarrow 0 \\ k \rightarrow 0}} \frac{E(a+h, b+k)}{\sqrt{h^2+k^2}} = 0 \text{ where } f(x, y) = L(x, y) + E(x, y)$$

$\frac{1}{2} L(x, y)$  is the tangent plane at  $(a, b)$

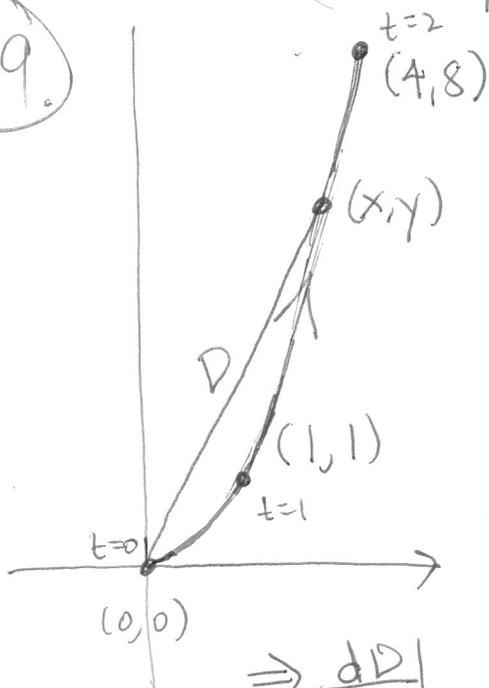
#7. False. The partials existing only says something about the slope in two directions. Differentiability means the function is locally planar, so the slopes in various directions at a point must reflect the shape of a <sup>(tangent)</sup> plane at that point.

#8. 
$$\left(\frac{\partial z}{\partial s}\right)\left(\frac{\partial z}{\partial t}\right) = \left(\frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s}\right) \left(\frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial t}\right)$$

$$= (f_x \cdot 1 + f_y \cdot 1) (f_x \cdot 1 + f_y \cdot (-1))$$

$$= (f_x + f_y)(f_x - f_y) = f_x^2 - f_y^2$$

#9.



$$D(x, y) = \sqrt{x^2 + y^2}$$

You're asked to compute  $\frac{dD}{dt} \Big|_{t=1}$  when  $x(t) = t^2$  and  $y(t) = t^3$ .

$$\frac{dD}{dt} = \frac{\partial D}{\partial x} \frac{dx}{dt} + \frac{\partial D}{\partial y} \frac{dy}{dt}$$

$$= \frac{1}{2} \cdot \frac{2x}{\sqrt{x^2+y^2}} \cdot 2t + \frac{1}{2} \cdot \frac{2y}{\sqrt{x^2+y^2}} \cdot 3t^2$$

$$= \frac{1}{2} \frac{2t^2}{\sqrt{t^4+t^6}} \cdot 2t + \frac{1}{2} \cdot \frac{2t^3}{\sqrt{t^4+t^6}} \cdot 3t^2$$

$$\Rightarrow \frac{dD}{dt} \Big|_{t=1} = \frac{2}{\sqrt{2}} + \frac{3}{\sqrt{2}} = \boxed{\frac{5}{\sqrt{2}}}$$

$$\#10 \quad \nabla f(w, T) = \left\langle 0.16(-35.75)w^{-0.84} + 0.16(0.4275)Tw^{-0.84}, \right.$$

$$a) \quad \nabla f(5, 30) = \left\langle 0.16(-35.75)5^{-0.84} + 0.16(0.4275)(30)(5)^{-0.84}, \right. \\ \left. \approx \langle -0.949, 1.175 \rangle \right.$$

b) The wind chill increases at the greatest rate in the direction of  $\langle -0.949, 1.175 \rangle$  when  $w = 5$  mph and  $T = 30^\circ\text{F}$ .

c)  $|f_T(5, 30)| > |f_w(5, 30)|$  so a decrease in the temperature from  $30^\circ\text{F}$  would have a greater effect on the windchill than an increase in the wind speed.

$$\#11 \quad \frac{\partial Q}{\partial K} = \alpha b K^{\alpha-1} L^{1-\alpha} \quad \frac{\partial Q}{\partial L} = (1-\alpha)b K^\alpha L^{-\alpha}$$

$$\text{So } K \frac{\partial Q}{\partial K} + L \frac{\partial Q}{\partial L} = K(\alpha b K^{\alpha-1} L^{1-\alpha}) + L((1-\alpha)b K^\alpha L^{-\alpha}) \\ = \alpha b K^\alpha L^{1-\alpha} + (1-\alpha)b K^\alpha L^{1-\alpha} \\ = (\alpha b + (1-\alpha)b) K^\alpha L^{1-\alpha} = b K^\alpha L^{1-\alpha} = Q.$$

$$\#12 \quad a) \text{ Use the differential: } dT = T_x dx + T_y dy \\ \Delta T \approx dT = 4 \cdot (-0.02) + 3(0.03) = -0.08 + 0.09 \\ = 0.01$$

$$\text{So } T(1.98, 3.03) = T(2, 3) + \Delta T \\ \approx T(2, 3) + dT \\ = 65 + 0.01 = \underline{65.01}.$$

#13 Direction vector:  $\langle 5, -8 \rangle$

a) Line segment:  $\langle 2, 3 \rangle + t \langle 5, -8 \rangle$

$$\Rightarrow x(t) = 2 + 5t \Rightarrow (x(0), y(0)) = (2, 3)$$
$$y(t) = 3 - 8t \quad \nexists (x(1), y(1)) = (7, -5).$$

b) You need to slow the motion down by a factor of 4 because it takes 4 units of time to traverse the same line segment.

So replace  $t$  w/  $t/4 \dots$

You get  $x(t) = 2 + 5/4 t \quad \nexists y(t) = 3 - 2t$

Then  $(x(0), y(0)) = (2, 3) \quad \nexists (x(4), y(4)) = (7, -5).$

#14 a) Both  $f_x(0, 0)$  &  $f_y(0, 0)$  exist.

$$f_x(0, 0) = \lim_{h \rightarrow 0} \frac{f(0+h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h}$$

$$= \lim_{h \rightarrow 0} \frac{\frac{2h \cdot 0}{(h^2 + 0^2)^2} - 0}{h} = \lim_{h \rightarrow 0} \frac{0}{h} = 0$$

Similarly,  $f_y(0, 0) = 0$ . Note: Because  $f$  is piecewise defined at  $(0, 0)$ , you must use the formal definition of the partial derivative to compute  $f_x(0, 0)$  and  $f_y(0, 0)$ . If you were asked to compute  $f_x$  &  $f_y$  at any point other than  $(0, 0)$ , then you could have computed them by applying the quotient rule to  $\frac{2xy}{(x^2+y^2)^2}$  (and  $f_x, f_y$  would exist).

b) No  $\lim_{\substack{(x,y) \rightarrow (0,0) \\ \text{along } y=x}} f(x,y) = \lim_{x \rightarrow 0} \frac{2x^2}{(x^2+x^2)^2} = \lim_{x \rightarrow 0} \frac{1}{2x^2} \text{ DNE}$  If limit doesn't exist  $f$  can't be continuous.

c) NO.  $f$  differentiable implies  $f$  is continuous.  
 $f$  not continuous implies  $f$  is not differentiable.